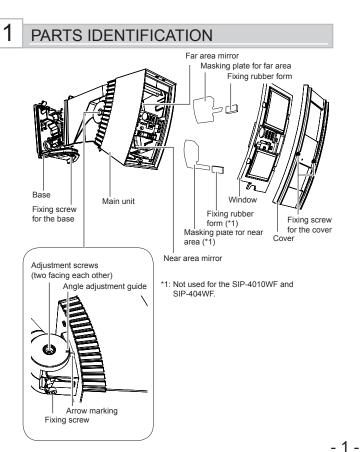


FEATURES

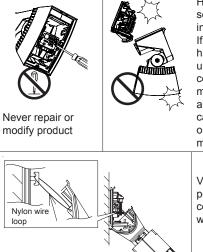
- Low power consumption (3-9VDC, 40µA (standby) 5mA max.)
- Low battery signal
- * Intelligent PIR Detection System
 - Three dual pyro-elements with patented Double Conductive Shielding
 - Detection of ambient temperature and illuminance for automatic sensitivity management
- Advanced detection algorithm
- * Anti-vandalism functions
 - Max.4 m (13 ft.) installation height
 - Anti-rotation function with accelerometer
 - Anti-masking function with photo-beam
- * Independent sensitivity selector for near/far areas
- Detection logic selector
- Detection range selector
- * Independent N.C. and N.O. ALARM output
- Adjustable alarm interval time
- Reinforced polycarbonate housing



- : Low current Synthesized Intelligent PIR
 - SIP-3020WF
 - SIP-4010WF
 - SIP-404WF

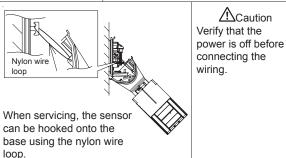


2 INSTALLATION AND MAINTENANCE NOTES

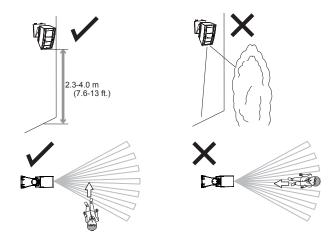


loop.

Hold the main unit securely when you install or service it. If you remove your hands from the main unit when cables are connected to it, the main unit may fall and the connector cables may break or the circuit board may be damaged.



ENGLISH



INSTALLATION HINTS

Mount the detector so that the majority of traffic flow is across the detection pattern.

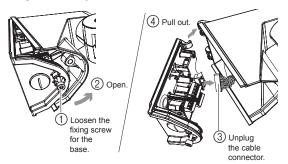
3 INSTALLATION AND ANGLE ADJUSTMENT

3-1 Wall Mounting

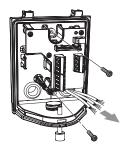
(1) Attach the paper template (an accessory) onto the wall, and drill a 6-mm dia. mounting hole and a cabling hole. Insert the anchor bolt (an accessory) into the board mount hole.

Distance from the ground to the bottom of the template must be between 2.3 m (7.6 ft.) and 4 m (13 ft.).

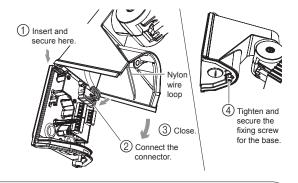
(2) Using an allen key, remove the main unit from the base.



(3) Drill through the bushing of the wiring hole, pass the cable through the hole, and secure the base to the wall.



- (4) Connect the cable to the terminal block (see Step 3-3).
- (5) Mount the main unit onto the base.



Cautions>>

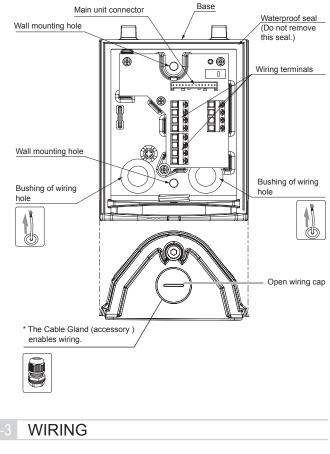
When mounting the main unit, take care not to trap the nylon wire loop. Also, take care not to get your fingers caught.

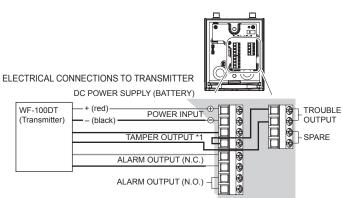
(6) Check to see that the various settings and operations are correct.

Caution>>

When the red LED flashes after the power turns on, this signifies that the system is warming up. Wait for approximately 120 seconds.

3-2 Inside View of the Base





*1: TAMPER terminals to be connected to a 24 hour supervisory loop.

Cautions>>

Maximum wiring length is 3 m.

Name	Function		
TROUBLE OUTPUT	Trouble out is used for anti-masking signal and low battery signal. When an object is placed close to the lens surface, for a period of more than 120 seconds (approx.), the IR anti-masking circuit will activate and generate a trouble signal. When the battery power is less than 2.3V DC, and this condition continues more than 2.5 hours, the signal will be generated.		
	It is detected when the cover is opened.		
	It is detected when the main unit is removed from its base.		
TAMPER OUTPUT	Anti-Rotation: Damage sustained by the main unit is detected. If the main unit is impacted in a horizontal or vertical direction and if the position of the main unit has changed, damage sustained by the main unit will be detected.		

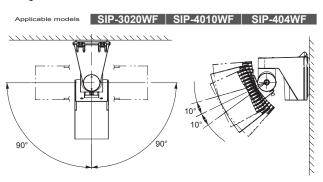
- 2 -

FRANÇAIS

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DETECTION AREA SETTING

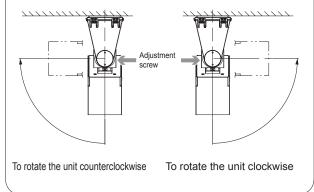
You can adjust the detection area by 90 degrees in a horizontal direction and by 10 degrees in a vertical direction. Correct the vertical detection angle according to the mounting height of the sensor unit.



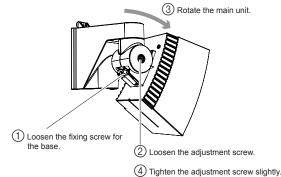
Cautions>>

4

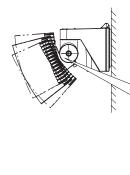
To rotate the main unit counterclockwise, loosen the RHside adjustment screw. To rotate the main unit clockwise, loosen the LH-side adjustment screw. Otherwise, you may find it difficult to tighten or you may find that you cannot tighten the adjustment screw when you are securing the main unit.



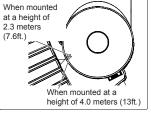
 Adjust the angle of the main unit in a horizontal direction so that you can cover the desired detection area.



(2) Adjust the angle of the main unit in a vertical direction so that you can cover the desired detection area.



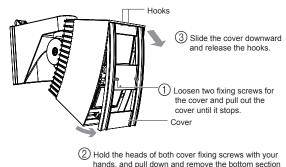
Align the arrow of the main unit with the "Angle adjustment guide" of the adjustment screw. The main unit is usually adjusted within the width of this guide.



Cautions>>

If the mounting wall is at an angle, the arrow of the main unit may exceed the top or bottom limit of "Angle adjustment guide". Always check this using the area viewfinder or the walk tester. If the detection area is too high or too low, an object outside the detection area may be detected or incorrect object detection may occur.

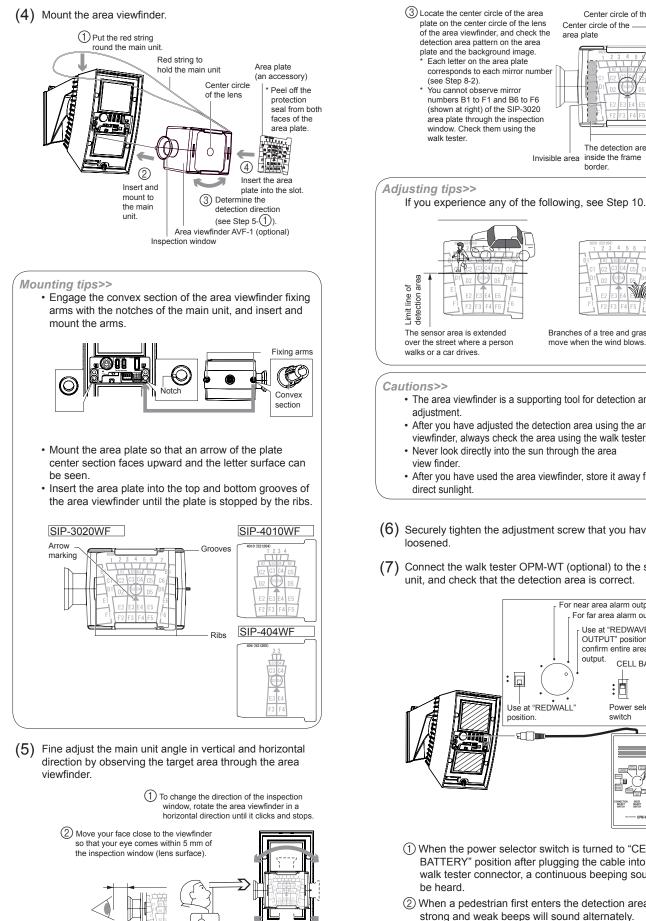
(3) Remove the cover.



hands, and pull down and remove the bottom section of the cover from the main unit.

Cautions>>

The cover is linked to the main unit by nylon wire loop so that the cover does not fall. Do not pull the cover using excessive force.



Branches of a tree and grass move when the wind blows

Invisible area

Center circle of the lens

The detection area is inside the frame

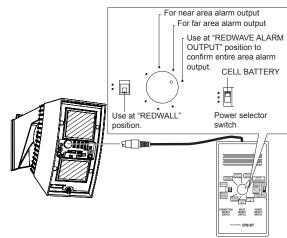
Center circle of the

border

area plate

· The area viewfinder is a supporting tool for detection area

- · After you have adjusted the detection area using the area
- viewfinder, always check the area using the walk tester.
- · Never look directly into the sun through the area
- · After you have used the area viewfinder, store it away from
- (6) Securely tighten the adjustment screw that you have
- (7) Connect the walk tester OPM-WT (optional) to the sensor unit, and check that the detection area is correct.



- (1) When the power selector switch is turned to "CELL BATTERY" position after plugging the cable into the walk tester connector, a continuous beeping sound will
- (2) When a pedestrian first enters the detection area, the strong and weak beeps will sound alternately.
- ③ When the entirety of a pedestrian's body is detected, the strong beep will sound continuously.

Cautions>>

 OPM-WT can not be operated at the "Power supply from sensor" position of the power select switch.

Cautions>>

When you are checking the detection area, take care not to cover the shaded area of the window with the walk tester or its cable. If infrared beams to the sensor are partially shielded, the detection sensitivity will drop and the detection operation may fail.

If it is difficult to detect an object>>

1. Set the detection logic switch to the "OR" position (see Step 5-2).

If the sensor is OK when you have completed the walk test, return the logic switch to the "AND" position.

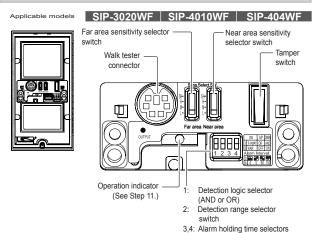
2. Adjust the sensor sensitivity switch (see Step 5-1).

To mask the detection area>>

Detection area	How to mask the area	Reference
	Use the switch.	5-3
Far area	Use the masking plate (mounted in the main unit).	Step 7
Near area	Use the masking plate (mounted in the main unit).	8-1
	Attach the masking seal (an accessory) to the area mirror surface.	8-2

FUNCTION SETTING

5



Cautions>>

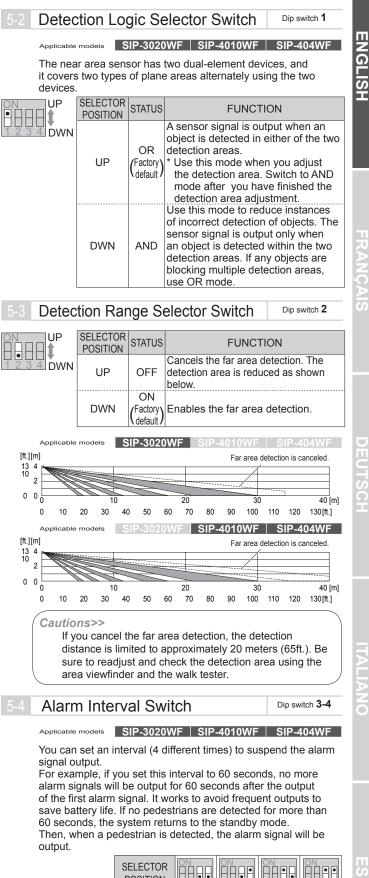
If the red LED keeps blinking for approx. 120 seconds after turning the power on, turn the power off and then on again.

Sensitivity Selector Switch for Near and Far Area

Applicable models SIP-3020WF SIP-4010WF SIP-404WF

You can change the sensitivity for far area detection and near area detection independently.

ns.Select.SW.	SELECTOR POSITION	FUNCTION
	SH	Suitable for sites requiring a level of sensitivity higher than "H"
	Н	Suitable for sites requiring a level of sensitivity higher than "M"
	M (Factory default)	Suitable for standard applications
	L	Suitable for hostile and narrow area



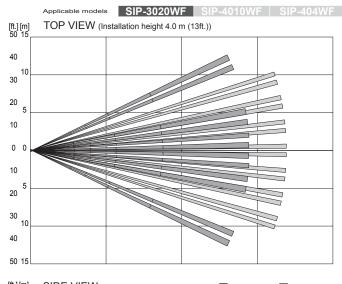
SELECTOR POSITION				$ \begin{array}{c} \text{ON}\\ 1 & 2 & 3 & 4 \end{array} $
FUNCTION	0 sec (Factory default)	5 sec	60 sec	150 sec

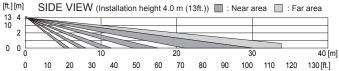
Cautions>>

The alarm interval is set to 0 sec as a factory default to allow the detection area to be correctly recognized for the Walk-test. Set the alarm interval switch after adjusting the detection area

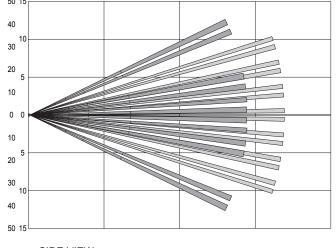
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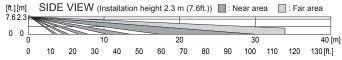
6 DETECTION AREA





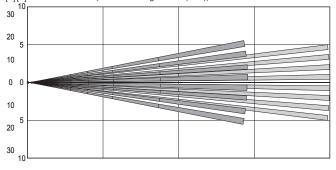


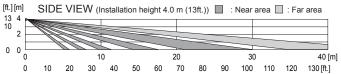


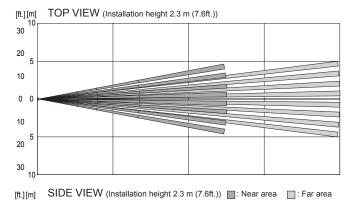


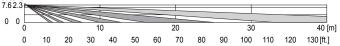
 Applicable models
 SIP-3020WF
 SIP-4010WF
 SIP-404WF

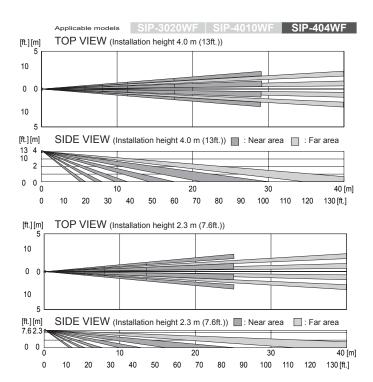
 [ft.][m]
 TOP VIEW (Installation height 4.0 m (13ft.))











MASKING THE FAR AREA SENSOR

The far area mirror mounted in the main unit has 2 far masking plates; one at the right side of this mirror and the other at the left side of this mirror. You can mask the detection area by changing the position of these masking plates.

Cautions>>

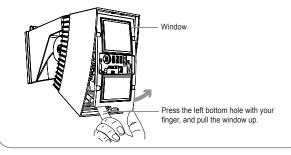
7

- You can only mask the detection area from its outside to its inside using the masking plates. You cannot mask only the inside detection area.
- However, if you need to mask the inside detection area only, use the white space (margin) of the near area masking seal (an accessory) for the masking. Attach the seal and mask all mirrors that you need to shield.

Cautions>>

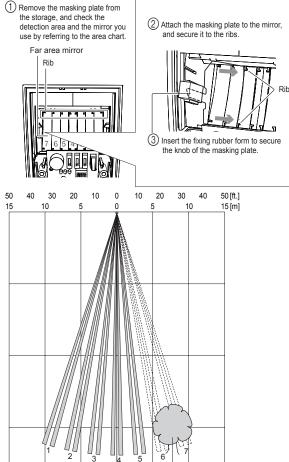
- · The window is linked to the main unit by nylon wire loop so that the window does not fall. Do not pull the window using excessive force.
- · After you have masked the detection areas, mount the window and place the excessive nylon wire loop inside the main unit.

How to remove the window>>

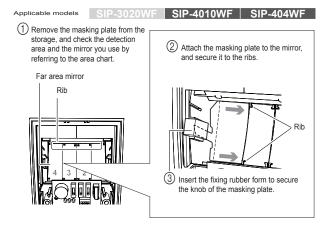


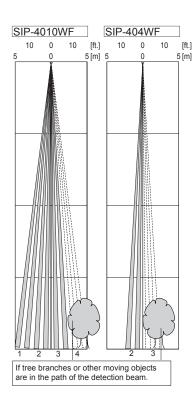






If tree branches or other moving objects are in the path of the detection beam.



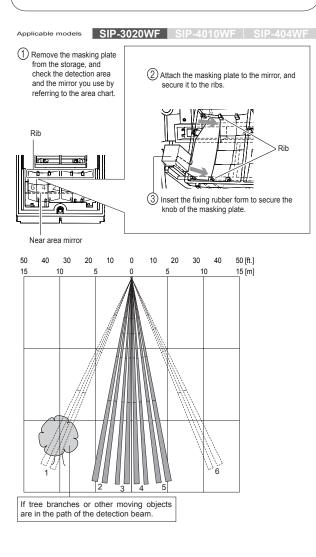


Masking the Detection Areas using Masking Plates

The near area mirror mounted in the main unit has 2 near masking plates; one at the right side of this mirror and another at the left side of this mirror. You can mask the detection area by changing the position of these masking plates.

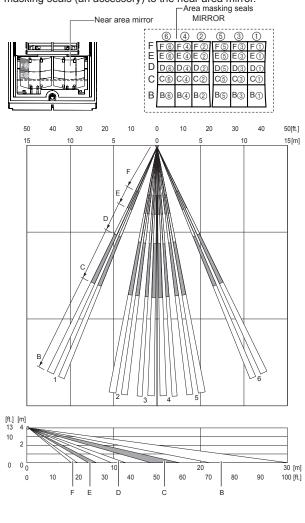
Cautions>>

You can mask the outside detection areas only; they are areas 1 and 6. Use the area masking seals (an accessory) to mask the other detection areas (see Step 8-2).



B-2 Masking the Detection Areas using Masking Seals

Using the tweezers (an accessory), carefully attach the area masking seals (an accessory) to the near area mirror.

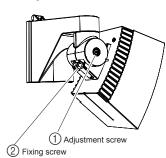


Points>>

If you are using the SIP-3020WF, SIP-4010WF, or SIP-404WF sensor unit when you have completed Step 8, proceed to Step 9.

Applicable models SIP-3020WF SIP-4010WF SIP-404WF

(1) After you have adjusted all sensor items, securely tighten all adjustment screws that you have loosened. Finally, securely tighten the bottom fixing screws.



Cautions>>

- If you need to adjust the detection area again, be sure to loosen the fixing screw. If you try to move the main unit without loosening the fixing screw, the unit may be damaged.
- When you mount the cover, place the excessive nylon wire loop in the main unit. If the wire has been pinched by the window and the cover, rain drops may be able to enter into the main unit.

(2) Mount the cover.

10 OPERATION TEST

If There is a Public Street Where a People Walk or Cars Drive by the Detection Area

Points>>

Reduce the size of the detection area so that it does not include any public streets.

- (1) Check to see that the arrow of the main unit is within the width of "Angle adjustment guide" on the adjustment screw.
- (2) Using the area viewfinder, check to see that the detection area does not include any public streets.
- (3) If the detection area does go beyond a public street, correct the vertical angle of the main unit. However, exercise care so that the arrow does not move away significantly from the "Angle adjustment guide" position.

If the arrow does move away significantly from the "Angle adjustment guide" position:

Mask the far area detection area using the masking plate or by using the far area masking switch. You may be required to also mask the near area detection area under specific sensor installation conditions (see Steps 5 and 8).

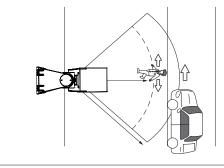
(4) When a person walks along the street or a car drives along it, check the detection area using the walk tester.

Points>>

You cannot mount and use both the area viewfinder and walk tester simultaneously.

Cautions>>

The detection area may increase if there is a large difference in temperature between the moving object and the background.



Cautions>>

- 9 -

A heat source beyond the detection area may cause a false alarm due to the reflection of heat off the ground. Examples of types of surfaces that reflect include water (puddles), wet roads, smooth concrete surfaces and asphalt roads.

If the source of the heat is strong and/or the reflection rate is high, the detection distance will be longer than required and may detect unnecessary objects beyond the target area. Therefore, select the detection range position according to the ground conditions of the installation site.



2 If Tree Branches or Grass are Detected When They Move Within the Detection Area

Points>>

Adjust the detection area so that it does not cover tree branches or grass that move when the wind blows.

- Check to see that the arrow of the main unit is within the width of "Angle adjustment guide" on the adjustment screw.
- (2) Using the area viewfinder, check to see that the detection area does not cover tree branches or grass that may move when the wind blows.
- (3) Use the walk tester to listen for sound level changes when there is no apparent activity in the detection area. Adjust the detection area so that it does not detect unwanted areas.
 - J.

If the sound level changes, some part of the detection area must be active (i.e.: an object is moving).

- (4) Use the walk tester and locate the part of the detection area that is active. Change the walk tester selector switch position and determine whether the active part of the detection area is far or near.
- (5) Using the area viewfinder again, locate the active detection area.
- (6) Mask the active detection area. To do this, mask the area using the masking plate or the masking seal. Otherwise mask the area using the far area masking switch (see Steps 5, 7, and 8).
- (7) Using the walk tester again, check that the sound level changes. If the sound level does not change excessively, you can finish the adjustment.

Points>>

You cannot mount and use both the area viewfinder and the walk tester simultaneously.

11 LED FUNCTIONS



— Operation indicator - Red LED

Cautions>>

If the red LED keeps blinking for approx. 120 seconds after turning the power on, turn the power off and then on again.

DETECTOR STATUS	If the cover is removed	
During power ON	Blinks.	
During standby	Turns OFF.	
When detected (in far/near area)	Lights.	

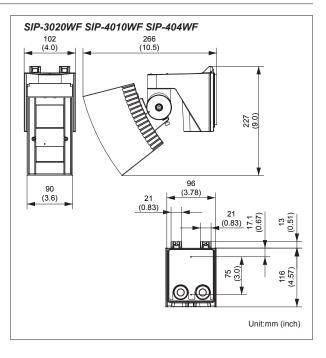
12 SPECIFICATIONS

12-1 Specifications of the Main Unit

Applicable models SIP-3020WF SIP-4010WF SIP-404WF

Applicable models SIP-3020WF SIP-4010WF SIP-404WF				
Model	SIP-3020WF	SIP-4010WF	SIP-404WF	
Detection method	Passive infrared			
Coverage	30 x 20m (100 x 65ft.)	40 x 10m (130 x 33ft.)	40 x 4m (130 x 13ft.)	
Number of detection zones	74 zones	48 zones	24 zones	
Mounting height	2.3 to 4m (7.6 to 13ft.)			
Power input	3 - 9V DC Alkaline or lithium battery			
Operating voltage	2.5 - 10V DC			
Current draw	40 μA (standby) 5mA max. (operating, LED ON)			
Operation indicator	RED ALARM			
Warm-up period	Approx. 120 sec.			
Detection range selector	Far area: ON / OFF			
Alarm interval period	0 / 5 / 60 / 150 sec.			
Detection logic selector	AND/OR			
Tamper output	N.C. 10V DC, 0.01A max.			
Trouble output	N.C. 10V DC, 0.01A max.			
Alarm output	N.C. 10V DC, 0.01A max. N.O. 10V DC, 0.01A max.			
Sensitivity selector	Far: SH/H/M/L Near: SH/H/M/L			
Operating temperature	-25 to +60°C (-13 to +140°F)			
IP rating	Main unit: IP65 Chassis: IP55			
Dimensions (H × W × D)	227 x 102 x 266mm (9 x 4 x 10.5 in.)			
Weight	1.2kg (42 oz.)			
Accessories	Screws, paper template, allen key, area masking seal, tweezers, instruction manual, area plate, fixing rubber form, cable glands			

DIMENSION



OPTION

- OPM-WT • AVF-1
 - /T -Audio Walk Tester -Area View Finder
- SIP-MINIHOOD
- -Area View Finder -Sun/Snow shield

These units are designed to detect movement to activate CCTV system. Being only part of a complete surveillance system, we cannot accept responsibility for any damage or other consequences resulting form the activation of the unit. This product confirms the EMC Directive 2004/108/EC.

Specifications and design are subject to change without prior notice.



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