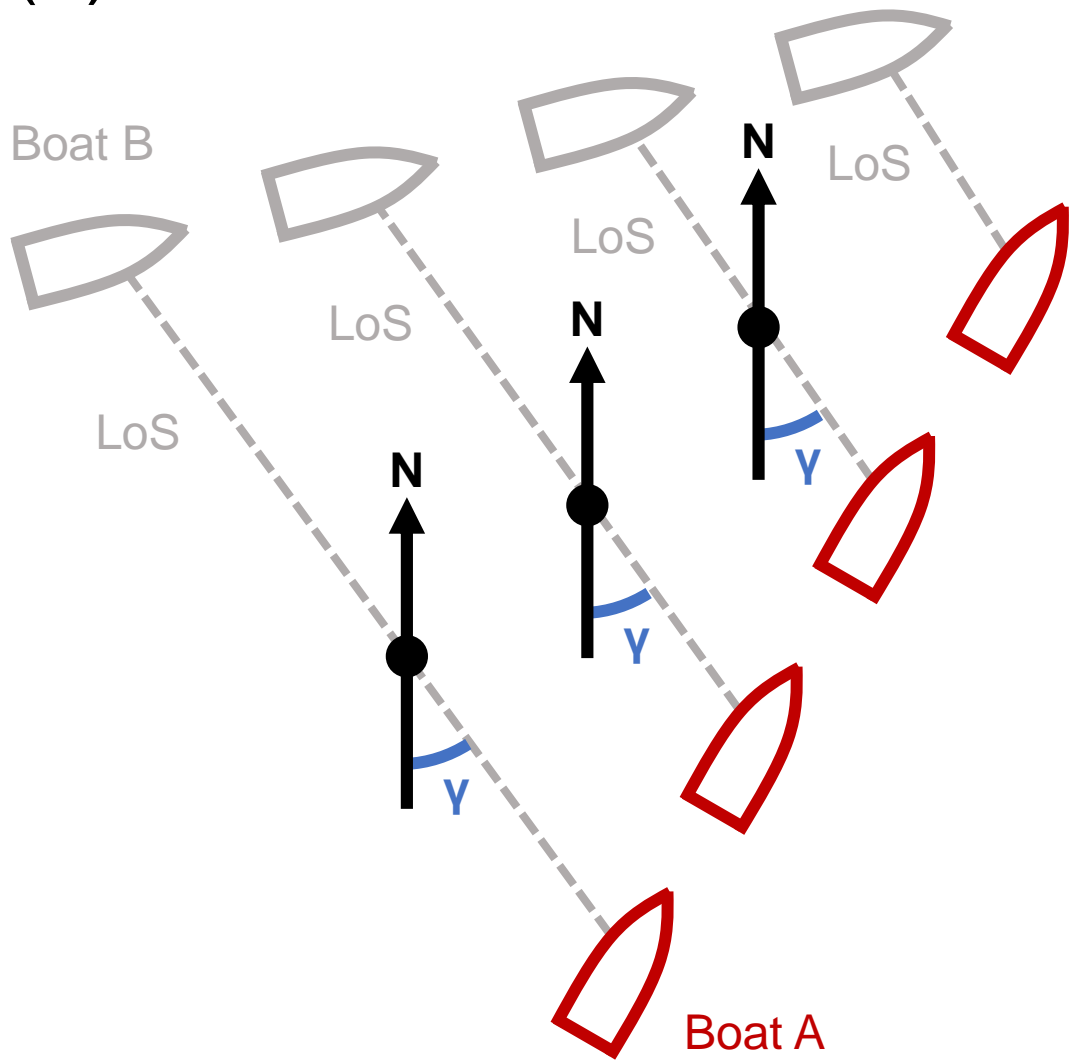
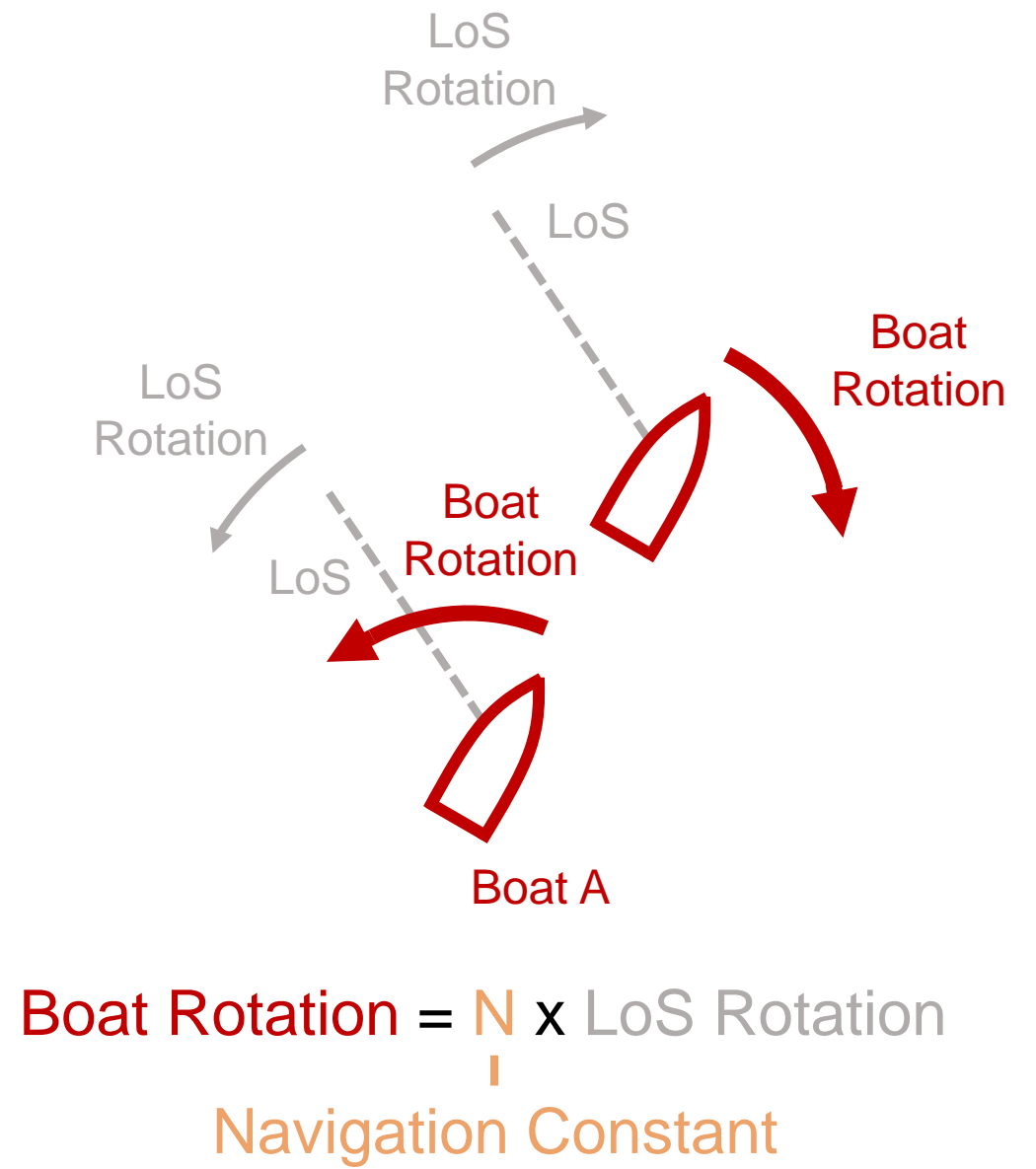


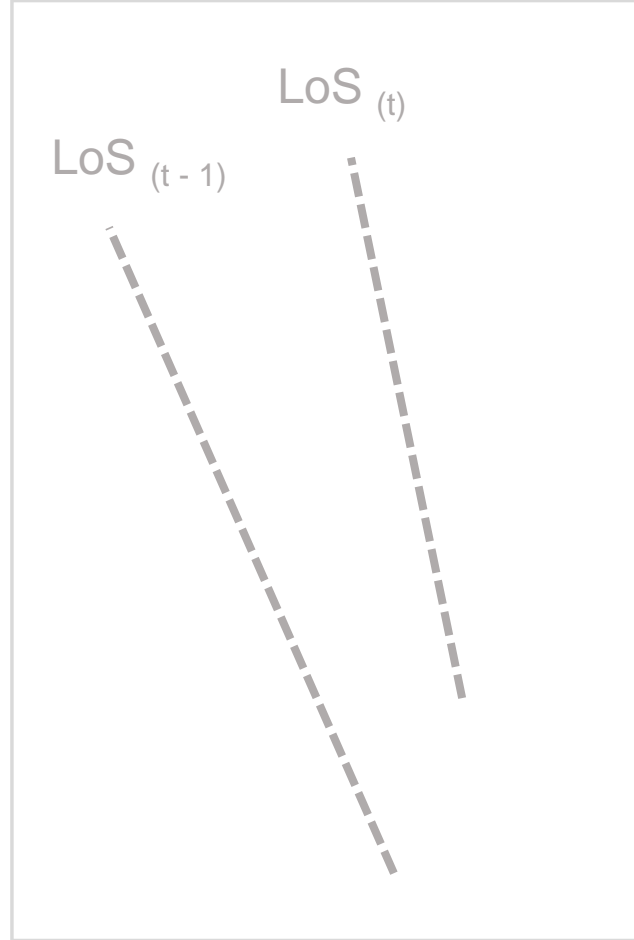
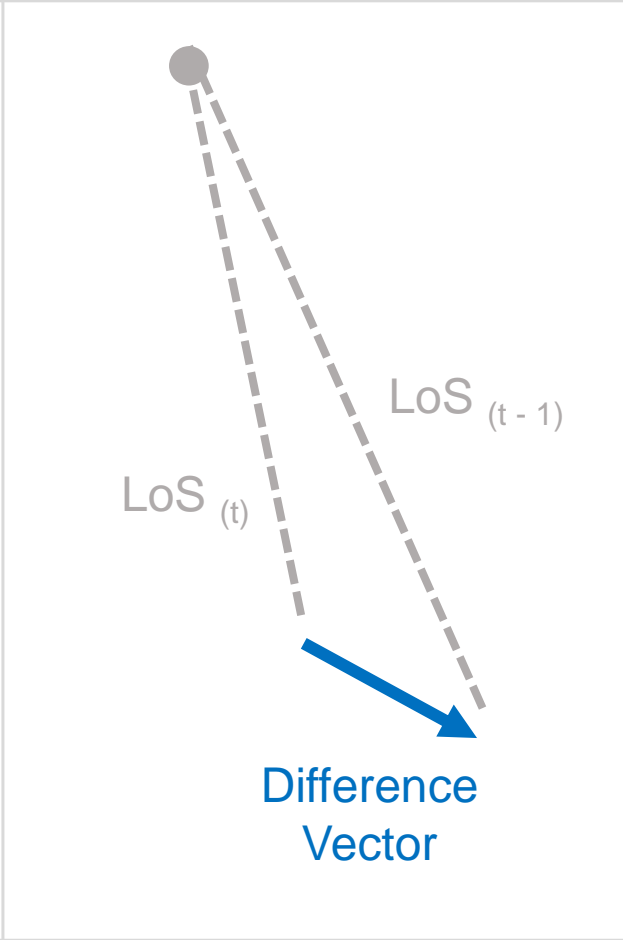
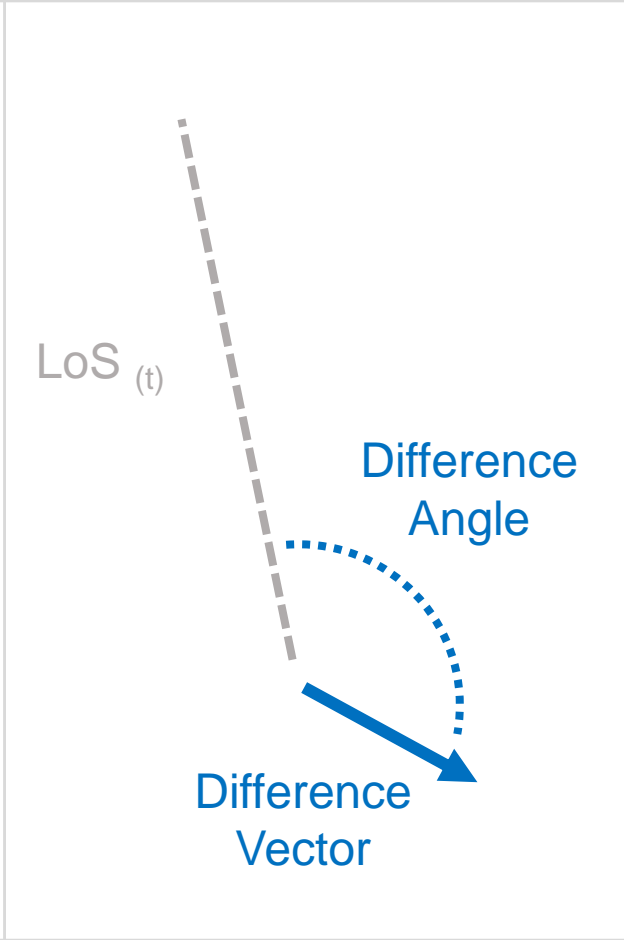
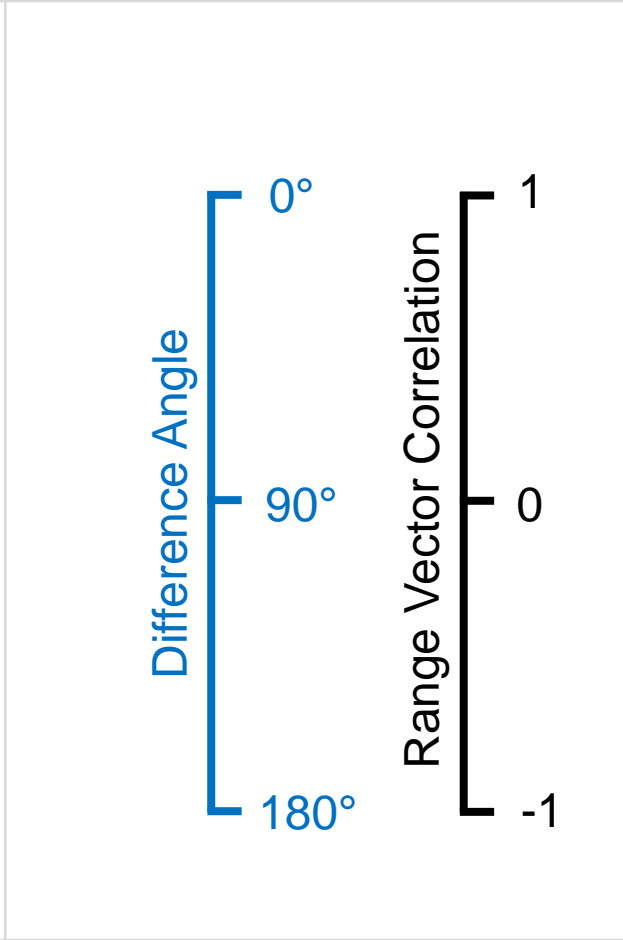
(a) Parallel Navigation



(b) Proportional Navigation



(c) Range Vector Correlation

Step 1	Step 2	Step 3	Step 4
			
<p>Obtain lines-of-sight between target and interceptor.</p>	<p>Obtain the time derivative difference vectors of LoS.</p>	<p>Measure the angle between difference vectors and LoS.</p>	<p>Convert the difference angle to correlation value.</p>