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HHARNet: Taking inspiration from Inception and Dense Networks for Human Activity Recognition using Inertial Sensors

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Abstract—Human Activity Recognition (HAR) an important area of research in the light of enormous applications that it provides, such as health monitoring, sports, entertainment, efficient human computer interface, child care, education and many more. Use of Computer Vision for Human Activity Recognition has many limitations. The use of inertial sensors which include accelerometer and gyroscopic sensors for HAR is becoming the norm these days considering their benefits over traditional Computer Vision techniques. In this paper we have proposed a 1-dimensional Convolutions Neural Network which is inspired by two state-of-the art architectures proposed for image classifications; namely Inception Net and Dense Net. We have evaluated its performance on two different publicly available datasets for HAR. Precision, Recall, F1-measure and accuracies are reported.

Keywords—Human Activity Recognition (HAR), Activity Classification, Deep Neural Networks, Inertial Sensors based classification, Digital Signal Processing, Computer Vision Inspired 1D-CNN

I. INTRODUCTION

Human activity recognition is currently an active area of research. The list of its functional areas includes, but is not limited to, care for the elderly, child monitoring, education, entertainment, environmental support, sports, etc. Human Activity Recognition is part of the Body Area Network, which complements the Wireless Sensor Network [3]. Many drawbacks have been identified when traditional computer vision methods have been used for HAR [4] [5], which include: 1) confidentiality; 2) environmental impact; 3) higher operating costs; 4) occlusion; 5) reduced portability; and the list continues.

New advancements have recently been made in the field of recognition of human activity, which is the use of inertial sensors. This fast-paced growth of micro-electromechanical systems (MEMS) has paved the way for some major, applicable and scientific breakthroughs in a wide range of research areas. Undoubtedly inertial sensors are one of the most significant MEMS sensors used collectively as Inertial Measurement Units (IMUs). Due to many positive features such as low cost, low power consumption, light weight and portability, the use of inertial sensors has increased in all

applications directly or indirectly connected to motion. By using advanced techniques, the data directly acquired for these sensors can be processed and used for complex motion analysis [6] [7].

Benefits of using sensor data exceed that of traditional computer-vision techniques. HAR uses many different types of sensors such as accelerometer, heart rate sensors and gyroscopes etc. The usage of data from these types of sensors covers all drawbacks of computer-vision techniques. The literature is composed of descriptive work of the applications inclusive of Machine Learning (ML) and Deep Neural Networks (DNN) Techniques used for HAR. An architecture working on the basis of inertial sensor data has been proposed by us in this paper whose inspiration stems from computer-vision architectures similar to those proposed for image recognition.

SMARTPHONE Dataset [8], Wireless Sensor Data Mining (WISDM) Activity Prediction [9] are the two diverse datasets which were used for performance evaluation. SMARTPHONE dataset comprises the readings from the accelerometer sensor and gyroscope sensor of a smartphone while the rest of the datasets are only limited to that of accelerometers. We have used raw sensor values for our experiments regardless of the feature engineering which has been done by contributors of datasets. This makes our work completely a Deep Learning approach which removes the necessity of having domain knowledge. Complete details of these datasets can be found in Section III.

Our proposed architecture is composed of inception modules [10] which is a combination of one-dimensional convolutional layers. Furthermore, all the feature maps are also linked similarly to the DenseNet network [11]. The parameter of accuracy has widely been used as a measurement of performance for experiments similar to our work but the usage of unbalanced datasets nulls its characteristics. Therefore, we have reported F1 score, Precision and Recall in conjunction with accuracy for these two datasets.

The presented paper is a part of very initial work form our active research. Our contributions in this article are explained below

- We have presented a novel 1 dimensional convolutional neural network which is inspired by Inception and Dense Net Architectures.
- We have evaluated its performance on two different human activity recognition datasets.

Section II includes a literature review; Section III outlines the architecture proposed; Section IV discusses the architecture evaluation datasets used; Section V discusses the findings obtained; Section VI explains the training process; Section VII explains specifics of implementation; Section VIII concludes the paper.

II. LITERATURE REVIEW

In [1] C. Xu, D et al. have created a Deep Neural Network they named it InnoHAR. It is based on the combination of Inception Neural Network and GRU layers. They conducted experiments on 3 different datasets including OPPORTUNITY Dataset, PAMAP2 Dataset, SMARTPHONE Dataset. In the case of Opportunity Dataset, they only used values from on-body sensors which include inertial measurement units and 3-axis accelerometers. In the case of the PAMPA2 dataset they download-sampled the accelerometer data to 33.3 Hz. They have used F-measure for performance evaluation. They achieved 0.946, 0.935 and 0.945 values of F-measure for OPPORTUNITY, PAMAP2 and SMARTPHONE Datasets respectively.

Researchers in [12] have proposed a One-dimensional convolution neural network for human activity recognition. They used triaxial accelerometer data (x,y,z) from a smartphone and created its magnitude vector. They compared their architecture with Random Forest Classifier. They achieved an accuracy of 92.71%. The dataset used had only 3 classes of Walk, Run and Still.

In [13] researchers have used mobile inertial sensors for the detection of human activities. They performed feature engineering on sensor data. Then used techniques including Linear Discriminant Analysis (LDA) and Kernel Principal Component Analysis (KPCA) to get robust features. Deep Belief Neural Networks (DBN) was then trained on those features. Results were compared with SVM and ANN. They used a publicly available dataset with 12 classes. They achieved 95.85 % overall accuracy for their proposed DBN, for ANN they achieved 89.06% and for SVM they achieved 94.12%.

Event detection through transformed accelerometer information was achieved by the researchers in [14]. They convert input signals straight into a reference coordinate system based on the rotation matrix (Euler Angle Conversion) derived from gyroscope orientation angles and orientation detectors. The benefit of the conversion is that it enables the identification of behavior and the detection; remaining impartial to orientation sensors. Number of classes was 5. Experiment was conducted with a phone in the hand of the person, pants pocket, or handbag. The results show that 84.77 percent of normal orientation impartial accuracy is achieved, which is 17.26 percent better than those without transformation of inputs

III. PROPOSED ARCHITECTURE

DenseNet [11] made use of features from all levels, resulting in features of all kinds ranging from small features to large features. The classification based on all of these

features contributes to better model performance. InceptionNet Modules [10] uses various sizes of kernels. The advantage of this is that certain features can be best detected with certain kernel size and making use of all possible options enhances the chances of detection.

The combination of the structure of both modules should lead to an architecture that has both qualities and that should do better than existing architectures. We have named this module as ‘‘InceptionDense’’. We have used three different sized kernels after 1x1 convolutions. The previous feature maps outputs are also concatenated. It is depicted in the figure (figure 1) given below.

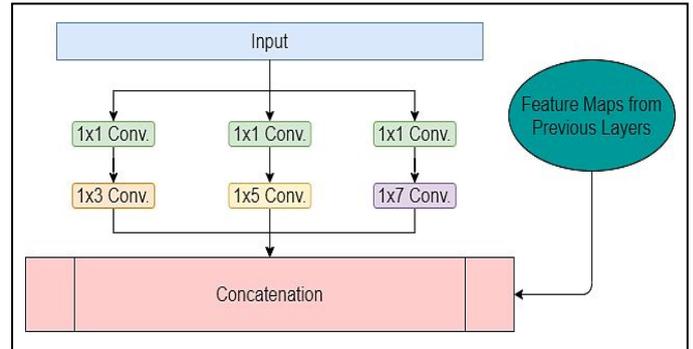


Fig. 1. InceptionDense - The Proposed Module

Figure 2 below shows the proposed architecture. We have used three InceptionDense modules of type shown in figure 1. The features channel from all the modules are being concatenated with the next module. There are no fully connected layers which reduces the number of parameters. We have made efficient use of 1x1 convolutions and reduced the number of filters to the number of classes which is 6 in case of all the datasets we have used for evaluation of our architecture. In the end we have use Global Average Pooling before Softmax/Prediction. Dropout of 0.50 was used after 1x1 layers before the InceptionDense Modules and before the last 1x1 layer which has 6 kernels.

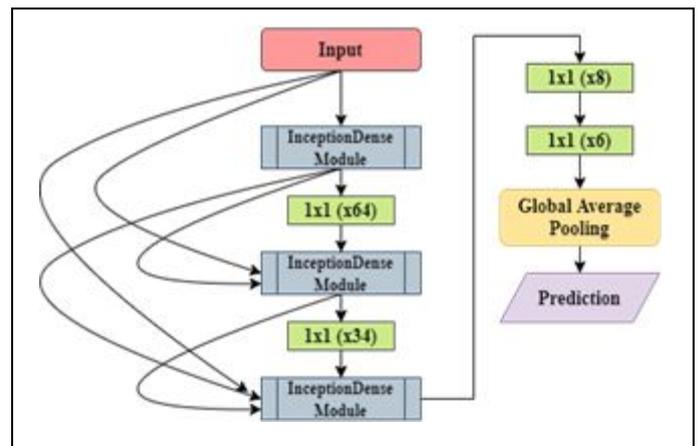


Fig. 2. Proposed Architecture

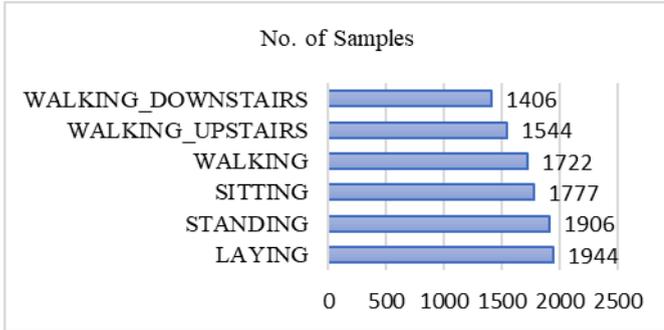
IV. DATASET USED

These three diverse datasets consisting of SMARTPHONE Dataset [8] and WISDM Activity Prediction [9] have been used to assess the performance of our architecture. Details regarding these datasets can be found below. Splitting of these datasets has been done as follows: 70% training and 15% validation and 15% testing.

A. SMARTPHONE Dataset

Dataset [8] consists of data taken from a gyrosopic sensor and an accelerometer of Smartphone named Galaxy SII which was given to the volunteers to be worn on their waist. A total of 30 volunteers were involved in the data collection experiment; having age between 19 to 48 and performing 6 activities whose classes distribution can be seen in the following table (table 1). A feature vector having 561 features was already created by the team in both time and frequency domain by the use of feature engineering. We have used raw values for sensors to train our Neural Network and have distributed the dataset into 70% training and 15% validation and 15% testing resulting in a balanced dataset.

TABLE I. SMARTPHONES DATASET CLASS DISTRIBUTIONS

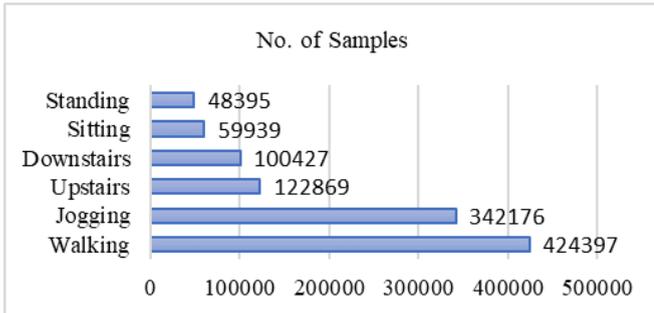


If compared to the other dataset, this dataset is fairly balanced.

A. WISDM Activity Prediction Dataset

This Dataset [9] consists of results obtained from controlled conditions in a laboratory and raw entries were 1,098,207. No missing values were found therefore requires no pre-processing. Classes distribution can be seen in table 2.

TABLE II. WISDM ACTIVITY PREDICTION DATASET CLASS DISTRIBUTION



As seen from the above histogram, the dataset is highly unbalanced.

V. RESULTS

Accuracy has been largely used in the related work but drawback with the majority of the inertial sensor collected dataset for HAR is its unbalance. By using these unbalanced datasets, Accuracy has become a less reliable parameter for measurement of performance. The same point has been stressed in [1] as well. Better parameters for measurement are F1 measure, Precision and Recall. A confusion matrix for a test set of values for which ground truth is known, is a table used commonly to visualize the performance of a classification model or classifier. A confusion matrix is a summary of the classification problem prediction results.

The number of correct and wrong forecasts are summarized by count values and split by class. Figure 4 below shows the Confusion Matrix for SMARTPHONE Dataset.

A. SMARTPHONE Dataset Results

The accuracy achieved for this dataset was 89.44 % on test data. Confusion matrix is given in the figure (figure 3) Detailed Performance Report is shown in figure 4. It can be observed from Confusion matrix that the neural network struggles the most in differentiate between “Sitting” and “Standing” classes with misclassification count of 182.

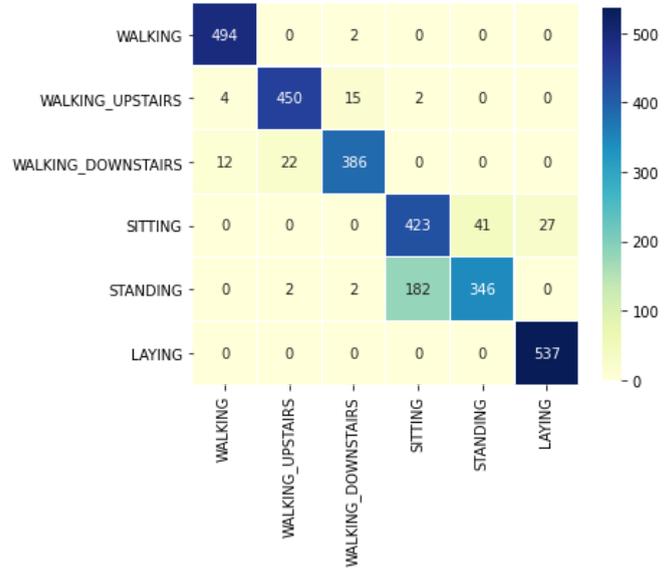


Fig. 3. Confusion Matrix SMARTPHONE Dataset

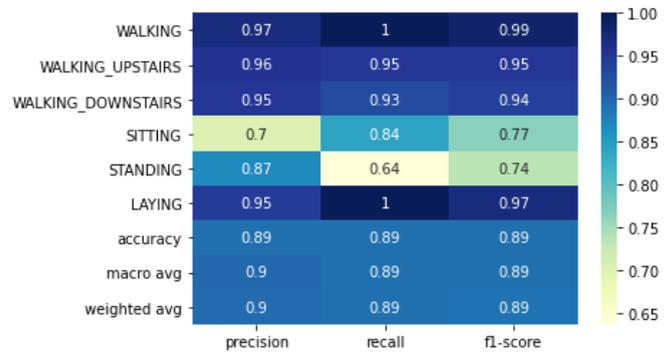


Fig. 4. Performance Report SMARTPHONE Dataset

B. WISDM Activity Prediction Dataset

The accuracy achieved for this dataset was 95.26 % on test data. Confusion matrix is given in the figure below (figure 5). Detailed Performance Report is shown in figure 6

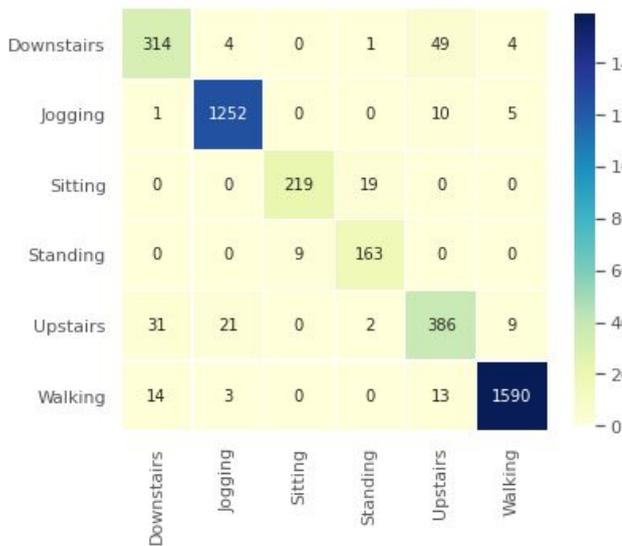


Fig. 5. Confusion Matrix WISDM Activity Prediction Dataset

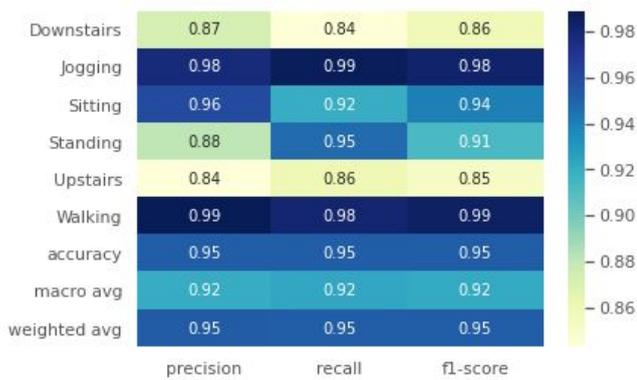


Fig. 6. Performance Report WISDM Activity Prediction Dataset

VI. TRAINING PROCESS

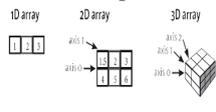
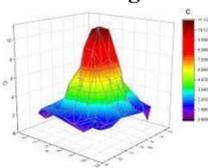
"Adam" and "RMSprop" optimizers were used in our experiments which gave us the result that "RMSprop" is preferred for SMARTPHONE dataset but "Adam" performed better for other dataset.

VII. IMPLEMENTATION DETAILS

The entire experiment was performed in Google's Collaboratory, GPU runtime environment. The list of major packages used along with their version numbers is shown in the table (table 3 below)

TABLE III. SOFTWARE STACK USED

Platform	Google Colaboratory	
Category	Name	Version
Deep and Machine Learning Libraries	 TensorFlow	2.3.0
	 Keras	2.4.3

 Sciklearn	0.22.2.post1
Data Manipulation 1D array 2D array 3D array 	1.18.5
 Numpy	1.0.5
 Pandas	3.2.2
Plotting 	0.10.1
 Matplotlib	0.10.1
 Seaborn	0.10.1

VIII. CONCLUSION

Human Activity Recognition is an Active area of research with applications in diverse fields. We have proposed a novel 1D-CNN which is inspired by InceptionNet [10] and DenseNet [11] and named it HHARNet. The architecture performance has been evaluated on SMARTPHONE Dataset [8] and WISDM Activity Prediction Dataset [9] an accuracy of 89.44% and 95.26% have being achieved respectively.

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